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1	 A communication interface for co
2	emulator device, the emulator device
3	instructions in lock-step with the DUT, th
4	a time dependent data transport p
5	between the DUT and the emulator devi-
6	a clock portion that supplies clock
7	device; wherein
8	the time dependent data transp
9	information depending upon an time p
10	emulator device.
11	
12	2. The communication interface a
13	dependent data transport portion compris
14	which carries bi-directional data.
15	
16	3. The communication interface a
17	dependent data transport portion compri
18	a first time dependent unidirection
19	to the emulator device; and
20	a second bi-directional time depe
21	
22	4. The communication interface acc
23	operate at varying clock speeds and
24	a system clock line; and
25	a line for supplying an internal c
26	device;
27	

oupling a device (DUT) under test with an implementing the DUT and executing ne communication interface comprising: portion that communicates serialized data ce; and k information to the DUT and the emulator port portion transports varying types of phase of operation of the DUT and the ccording to claim 1, wherein the time ises a plurality of data lines, at least one of ccording to claim 1, wherein the time ises: al data line that carries data from the DUT endent data line. cording to claim 1, wherein the DUT can wherein the clock portion comprises:

clock signal from the DUT to the emulator

Docket No.: CYPR-CD00185

1	5.	A communication interface, comprising:		
2		an interface;		
3		a microcontroller;		
4		an emulator device implementing a microcontroller and executing		
5	instru	uctions;		
6		wherein the microcontroller is coupled to the emulator device via the		
7	interf	face, the microcontroller executing the instructions in lock-step with the		
8	emul	emulator device; and		
9		wherein the interface comprises:		
10		a first time dependent data line;		
11		a second bi-directional time dependent data line;		
<u>_</u> 12		a third line for supplying an internal clock signal from the		
13		microcontroller; and		
14		a system clock line.		
14 15				
16	6.	The communication interface according to claim 5, wherein the emulator		
17	devid	ce comprises a field programmable gate array (FPGA).		
18				
19	7.	The communication interface according to claim 5, wherein the first time		
_ 20	depe	endent data line is used to convey information regarding pending interrupts.		
21				
22	8.	The communication interface according to claim 5, wherein the second bi-		
23	direc	ctional time dependent data line carries break signals.		
24				
25	9.	The communication interface according to claim 5, wherein the interface		
26	lines	are carried over a Category five cable.		
27				
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The communication interface according to claim 5, wherein register 10. read/write commands are conveyed over the first and second data lines when the microcontroller is in a halted mode.

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11. The communication interface according to claim 5, wherein the first and second data lines are used to convey register information from the microcontroller to the emulator device when the microcontroller is in a halted mode.

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12. The communication interface according to claim 5, wherein the first and second data lines are used to communicated I/O read, interrupt vector and watchdog timer information when the microcontroller is running.

13. The communication interface according to claim 5, wherein commands and data for the microcontroller are communicated over the interface for programming flash memory forming a part of the microcontroller.

14. The communication interface according to claim 5, wherein the clock frequency of the microcontroller is programmable, and wherein the clock is supplied to the emulator device over the third line of the interface.

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15. The communication interface according to claim 5, wherein the microcontroller transfers I/O data over the interface at a rate adequate to permit the emulator device to process the I/O data before execution of a next instruction and thus keep the microcontroller and the emulation device in synchronization.

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16. The communication interface according to claim 5, wherein the microcontroller uses the interface to return register information when in a halted mode, and to send I/O read, interrupt vector, and watchdog information when not in a halted mode.

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> Docket No.: CYPR-CD00185 -27-**PATENT**

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2	a microcontroller with an emulator device functioning as a virtual microcontroller,			
3	comprising:			
4	a first interface line carrying a system clock driven by the microcontroller, for			
5	driving the communication state machines forming a part of the virtual			
6	microcontroller;			
7	a second interface line carrying an internal microcontroller CPU clock;			
8	a third interface line for use by the microcontroller to send I/O data to the ICE			
9	and to notify the ICE of pending interrupts; and			
10	a fourth interface line for bi-directional communication that is used by the			
11	microcontroller to send I/O data to the ICE, and that is used by the ICE to convey			
12	halt requests to the microcontroller.			
13				
14	18. The apparatus according to claim 17, wherein the system clock runs at a			
15	first clock rate, unless the internal microcontroller CPU clock is running at the first			
16	clock rate in which case the system clock switches to two times the first clock rate.			
17				
18	19. The apparatus according to claim 17, wherein the interface lines are carried			
19	over a Category five cable.			
20				
21	20. The apparatus according to claim 17, wherein register read/write commands			
22	are conveyed over the third and fourth interface lines when the microcontroller is			
23	in a halted mode.			
24				
25	21. The apparatus according to claim 17, wherein the third and fourth interface			
26	lines are used to convey register information from the microcontroller to the			
27	emulator device when the microcontroller is in a halted mode.			
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A four wire interface for use in an in-circuit emulation (ICE) system to couple

- 22. The apparatus according to claim 17, wherein the third and fourth interface lines are used to communicated I/O read, interrupt vector and watchdog timer information when the microcontroller is running.
- 23. The apparatus according to claim 17, wherein commands and data for the microcontroller are communicated over the third and fourth interface lines for programming flash memory forming a part of the microcontroller.
- 24. The apparatus according to claim 17, wherein test and control functions are carried over the third and fourth interface lines to carry out real-time trace functions.
- 25. The apparatus according to claim 17, wherein the microcontroller sends I/O data over the interface at a rate adequate to keep the microcontroller and the emulation device in synchronization.

26. A four wire interface for use in an in-circuit emulation (ICE) system to couple a microcontroller with an emulator device based on a field programmable gate array (FPGA) functioning as a virtual microcontroller, comprising:

a first interface line carrying a system clock driven by the microcontroller, for driving the communication state machines forming a part of the virtual microcontroller;

a second interface line carrying an internal microcontroller CPU clock, wherein the clock frequency of the microcontroller is programmable;

wherein the system clock runs at a first clock rate, unless the internal microcontroller CPU clock is running at the first clock rate in which case the system clock switches to two times the first clock rate;

a third interface line for use by the microcontroller to send I/O data to the ICE and to notify the ICE of pending interrupts;

a fourth interface line used for bi-directional communication that is used by the microcontroller to send I/O data to the ICE, and that is used by the ICE to convey halt requests to the microcontroller;

wherein register read/write commands are conveyed over the third and fourth interface lines when the microcontroller is in a halted mode and wherein the third and fourth interface lines are used to communicated I/O read, interrupt vector and watchdog timer information when the microcontroller is running;

wherein test and control functions are carried over the third and fourth interface lines to carry out real-time trace functions;

wherein the microcontroller sends I/O data over the interface at a rate adequate to keep the microcontroller and the emulation device in synchronization; and

wherein the interface lines are carried over a Category five cable.